# Implementing a B&C algorithm for Mixed-Integer Bilevel Linear Programming

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# **Bilevel Optimization**

• The general **Bilevel Optimization Problem** (optimistic version) reads:

$$\min_{x \in \mathbb{R}^{n_1}, y \in \mathbb{R}^{n_2}} F(x, y)$$

$$G(x, y) \le 0$$

$$y \in \arg\min_{y' \in \mathbb{R}^{n_2}} \{f(x, y') : g(x, y') \le 0\}$$

where *x* var.s only are controlled by the **leader**, while *y* var.s are computed by another player (the **follower**) solving a different problem.

- A very very hard problem even in a convex setting with continuous var.s only
- **Convergent** solution algorithms are problematic and typically require additional assumptions (binary/integer var.s or alike)

#### Example: 0-1 ILP

 A generic 0-1 ILP can be reformulated as the following linear & continuos bilevel problem

$$\min c^T x$$
$$Ax = b$$
$$x \in \{0, 1\}^n$$

 $\min c^T x$ Ax = b $x \in [0, 1]^n$ y = 0

$$y \in \arg\min_{y'} \{-\sum_{j=1}^n y'_j : y'_j \le x_j, y'_j \le 1 - x_j \ \forall j = 1, \dots, n\}$$

Note that y is fixed to 0 but it cannot be removed from the model!

# Reformulation

$$\min_{x \in \mathbb{R}^{n_1}, y \in \mathbb{R}^{n_2}} F(x, y)$$

$$G(x,y) \le 0$$
  
$$y \in \arg\min_{y' \in \mathbb{R}^{n_2}} \left\{ f(x,y') : g(x,y') \le 0 \right\}$$

• By defining the **value function** 

$$\Phi(x) = \min_{y \in \mathbb{R}^{n_2}} \{ f(x,y) : g(x,y) \le 0 \},\$$

the problem can be restated as

$$\min F(x, y)$$

$$G(x, y) \le 0$$

$$g(x, y) \le 0$$

$$f(x, y) \le \Phi(x)$$

$$(x, y) \in \mathbb{R}^{n}.$$

• Dropping the nonconvex condition  $f(x, y) \le \Phi(x)$  one gets the so-called **High Point Relaxation** (HPR)

# **Mixed-Integer Bilevel Linear Problems**

• We will focus the **Mixed-Integer Bilevel Linear** case (MIBLP)

 $egin{aligned} \min F(x,y) & & \ G(x,y) \leq 0 \ g(x,y) \leq 0 \ (x,y) \in \mathbb{R}^n \ f(x,y) \in \mathbb{R}^n \ f(x,y) \leq \varPhi(x) \ x_j ext{ integer}, & orall j \in J_1 \ y_j ext{ integer}, & orall j \in J_2, \end{aligned}$ 

where *F*, *G*, *f* and *g* are **linear** (actually, affine) **functions** 

• Note that  $f(x, y) \le \Phi(x)$  is **nonconvex** even when all y var.s are continuous

#### **MIBLP** statement

• Using standard LP notation, our MIBLP reads

$$egin{aligned} \min_{x,y} \, c_x^T x + c_y^T y \ & G_x x + G_y y \leq q \ & Ax + By \leq b \ & l \leq y \leq u \ & x_j ext{ integer}, \ & orall j \in J_x \ & y_j ext{ integer}, \ & orall j \in J_y \ & d^T y \leq \Phi(x) \end{aligned}$$

where for a given  $x = x^*$  one computes the value function by solving the following MILP:

$$\Phi(x^*) := \min_{y \in \mathbb{R}^{n_2}} \{ d^T y : By \le b - Ax^*, \quad l \le y \le u, \quad y_j \text{ integer } \forall j \in J_y \}.$$

# Example

#### • A notorious example from

J. Moore and J. Bard. The mixed integer linear bilevel programming problem. *Operations Research*, 38(5):911–921, 1990.



# Example (cont.d)

Value-function reformulation



# A MILP-based B&C solver

- Suppose you want to apply a **Branch-and-Cut** MILP solver to HPR
- Forget for a moment about internal heuristics (i.e., deactivate all of them), and assume the LP relaxation at each node is solved by the simplex algorithm
- What do we need to add to the MILP solver to handle a MIBLP?
- At each node, let **(x\*,y\*)** be the current **LP optimal vertex**:

*if*  $(x^*, y^*)$  is fractional  $\rightarrow$  branch as usual

*if (x\*,y\*)* is integer and  $f(x^*, y^*) \le \Phi(x^*) \rightarrow$  update the incumbent as usual

# The difficult case

- But, what can we do in third possible case, namely (x\*,y\*) is integer but not bilevel-feasible, i.e., when f(x\*, y\*) > Φ(x\*)?
- Question: how can we cut this integer (x\*,y\*)? Possible answers from the literature
  - If (x,y) is restricted to be **binary**, add **a no-good cut** requiring to flip at least one variable w.r.t.  $(x^*, y^*)$  or w.r.t.  $x^*$
  - If (x,y) is restricted to be **integer** and all MILP coeff.s are integer, add a cut requiring a slack of 1 for the sum of all the inequalities that are tight at  $(x^*, y^*)$
  - Are weak conditions as they do not addresses the **reason of** infeasibility by trying to enforce  $f(x^*, y^*) \le \Phi(x^*)$  somehow

# **Intersection Cuts (ICs)**

- Try and use of intersection cuts (Balas, 1971) instead
- ICs are a powerful tool to separate a point **x**\* from a set **X** by a linear cut



- All you need is
  - a **cone** pointed at  $\mathbf{x}^*$  containing all  $\mathbf{x} \in \mathbf{X}$
  - a convex set S with x\* (but no x ε X) in its strict interior
- If x\* vertex of an LP relaxation, a suitable cone comes for the LP basis

# **ICs for bilevel problems**

• Our idea is first illustrated on the Moore&Bard example



### Define a suitable bilevel-free set

• Take the LP vertex  $(x^*, y^*) = (2, 4) \rightarrow f(x^*, y^*) = y^* = 4 > Phi(x^*) = 2$ 



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### **Intersection cut**

• We can therefore generate the intersection cut  $y \le 2$  and repeat



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# A basic bilevel-free set

**Lemma 1.** For any feasible solution  $\hat{y}$  of the follower, the set

$$S(\hat{y}) = \{ (x, y) \in \mathbb{R}^n : f(x, y) \ge f(x, \hat{y}), \, g(x, \hat{y}) \le 0 \}$$
(10)

does not contain any bilevel-feasible point in its interior.

- Note:  $S(\hat{y})$  is a convex set (actually, a **polyhedron**) when *f* and *g* are affine functions, i.e., in the MIBLP case
- Separation algorithm: given an optimal <u>vertex</u> (x\*,y\*) of the LP relaxation of HPR
  - Solve the follower for *x*=*x*<sup>\*</sup> and get an optimal sol., say  $\hat{y}$
  - if  $(x^*, y^*)$  strictly inside  $S(\hat{y})$  then generate a violated IC using the LP-cone pointed at  $(x^*, y^*)$ together with the bilevel-free set  $S(\hat{y})$

# A technical issue...

However, the above does not lead to a proper MILP algorithm as a bilevel-infeasible integer vertex (x\*,y\*) can be on the frontier of the bilevel-free set S, so we cannot be sure to cut it by using our IC's



We need to define the bilevel-free set in a more clever way if we want be sure to cut (x\*,y\*)

# An enlarged bilevel-free set

• Assuming g(x,y) is integer for all integer HPR solutions, one can "move apart" the frontier of  $S(\hat{y})$  so as be sure that vertex  $(x^*,y^*)$  belongs to its interior

**Theorem 1.** Assume that g(x, y) is integer for all HPR solutions (x, y). Then, for any feasible solution  $\hat{y}$  of the follower, the extended set

 $S^{+}(\hat{y}) = \{(x, y) \in \mathbb{R}^{n} : f(x, y) \ge f(x, \hat{y}), \ g(x, \hat{y}) \le 1\}$ (11)

does not contain any bilevel-feasible point in its interior, where 1 denotes a vector of all one's.

- The corresponding IC is always violated by (x\*,y\*) → IC separation to be implemented in a lazy constraint/usercut callback to produce a (locally valid) violated cut → B&C solver for MIBLP
- Note: alternative bilevel-free sets can be defined to produce hopefully deeper ICs

# **IC** separation issues

- IC separation can be probematic, as we need to read the cone rays from the LP tableau → numerical accuracy can be a big issue here!
- For MILPs, ICs like Gomory cuts are not mandatory (so we can skip their generation in case of numerical problems), but for MIBLPs they are more instrumental #SeparateOrPerish
- Notation change: let  $\xi = (x, y) \in \mathbb{R}^n$

 $\min\{\hat{c}^T\xi:\hat{A}\xi=\hat{b},\xi\geq 0\}$  be the LP relaxation at a given node

 $S = \{\xi : g_i^T \xi \le g_{0i}, i = 1, ..., k\}$  be the bilevel-free set  $\bigvee_{i=1}^k (g_i^T \xi \ge g_{i0})$  be the **disjunction** to be satisfied by all feas. sol.s

# **Numerically safe ICs**

A **single** valid inequality can be obtained by taking, for each variable, the worst LHS coefficient (and RHS) in each disjunction

To be applied to a **reduced form** of each disjunction where the coefficient of all basic variables is zero (kind of LP reduced costs)

$$igvee_{i=1}^k (g_i^T \xi \geq g_{i0}) \ \bigvee_{i=1}^k (\overline{g}_i^T \xi \geq \overline{g}_{i0}) \ i=1$$

$$\bigvee_{i=1}^{k} (\frac{\overline{g}_{i}^{T}}{\overline{g}_{i0}} \xi \ge 1)$$

Algorithm 1: Intersection cut separation

**Input** : An LP vertex  $\xi^*$  along with its a associated LP basis  $\hat{B}$ ; the feasible-free polyhedron  $S = \{\xi : g_i^T \xi \leq g_{0i}, i = 1, ..., k\}$  and the associated valid disjunction  $\bigvee_{i=1}^k (g_i^T \xi \geq g_{i0})$  whose members are violated by  $\xi^*$ ;

**Output**: A valid intersection cut violated by  $\xi^*$ ;

1 for 
$$i := 1$$
 to  $k$  do  
2  $| (\overline{g}_i^T, \overline{g}_{i0}) := (g_i^T, g_{i0}) - u_i^T(\hat{A}, \hat{b})$ , where  $u_i^T = (g_i)_{\hat{B}}^T \hat{B}^{-1}$ 

3 end

4 for 
$$j := 1$$
 to  $n$  do  $\gamma_j := \max\{\overline{g}_{ij} / \overline{g}_{i0} : i \in \{1, ..., k\}\};$ 

**5 return** the violated cut  $\gamma^T \xi \geq 1$ 

#### Conclusions

- Mixed-Integer Bilevel Linear Programming is a **MILP** plus additional constr.s
- Intersection cuts can produce valuable information at the B&B nodes
- Sound MIBLP heuristics, preprocessing etc. (not discussed here) available
- Many instances from the literature can be **solved in a satisfactory way**
- **Binary** code available (ask Markus Sinnl for a free license)

#### Slides <a href="http://www.dei.unipd.it/~fisch/papers/slides/">http://www.dei.unipd.it/~fisch/papers/slides/</a>

#### **Reference papers:**

M. Fischetti, I. Ljubic, M. Monaci, M. Sinnl, "Intersection cuts for bilevel optimization", in Integer Programming and Combinatorial Optimization: 18th International Conference, IPCO 2016 Proceedings, 77-88, *Mathematical Programming* 172(1), 77-103, 2018

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