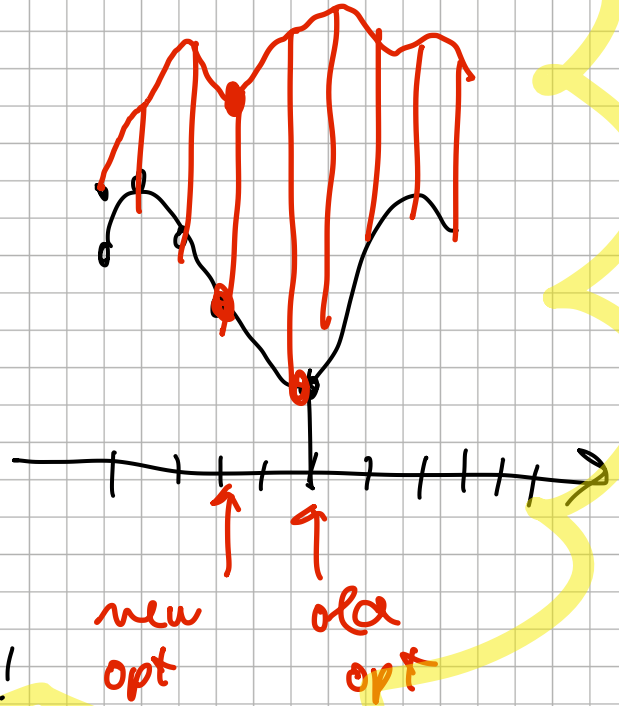
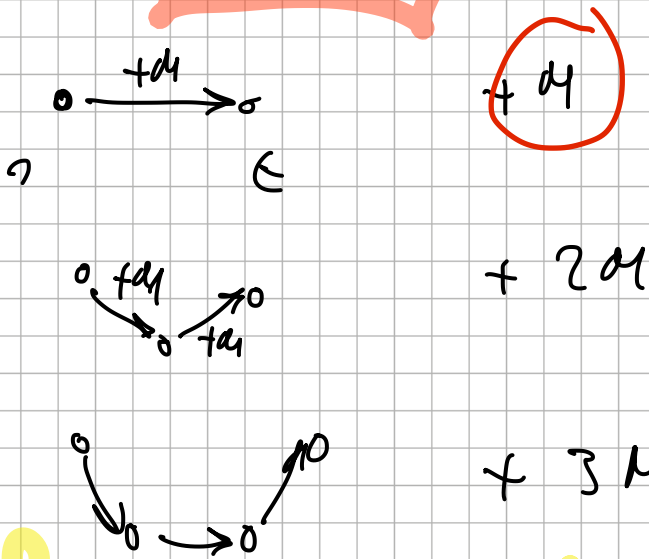


OR1 6-DEC-2021

CAN WE COMPUTE THE SHORTEST PATH ON MODIFIED COSTS?

$$c_{ij} \leftarrow c_{ij} + M \cdot \delta_{i,j}, \text{ with } M \gg 0$$



OPTIMAL PATH DEPENDS ON M !!

PROJECT PLANNING

Project = set of ACTIVITIES

A_1, A_2, \dots, A_m

each having a given duration

d_1, d_2, \dots, d_m

PRECEDENCE: $A_i \prec A_j$

activity A_j can start only when A_i is finished

DIRECTED GRAPH \Leftrightarrow project

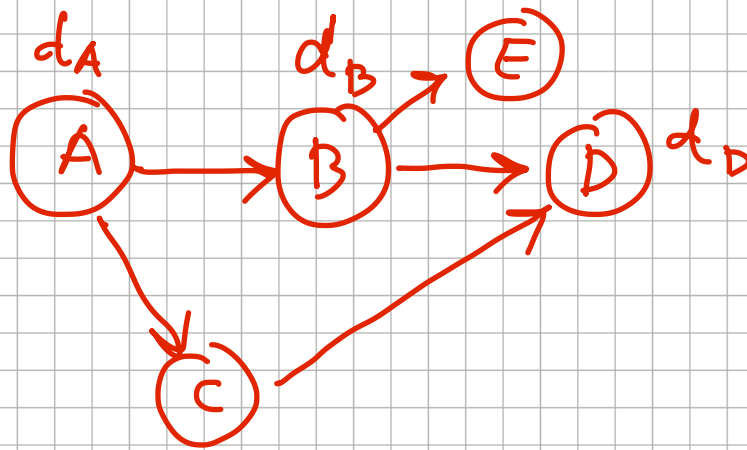
Ex: activities A, B, C, D, E

preced.

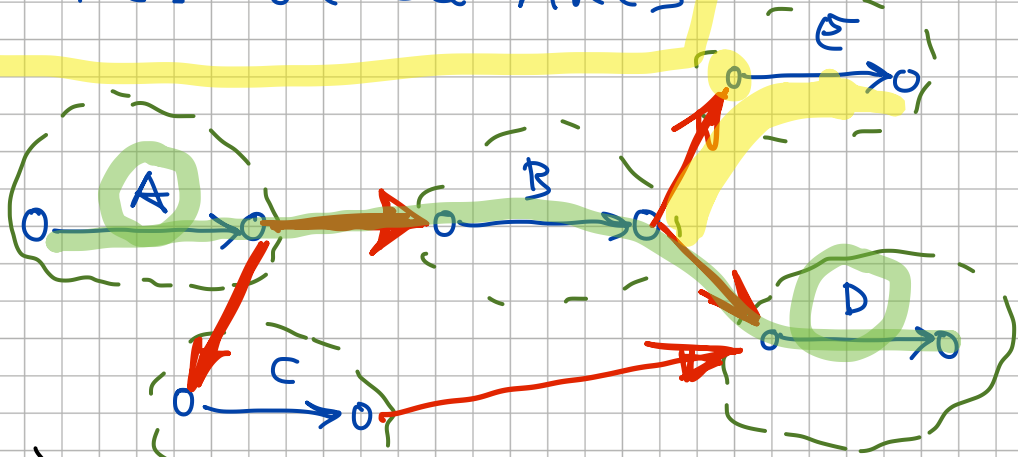
$A < B$, $A < C$

$B < D$, $C < D$, $B < E$

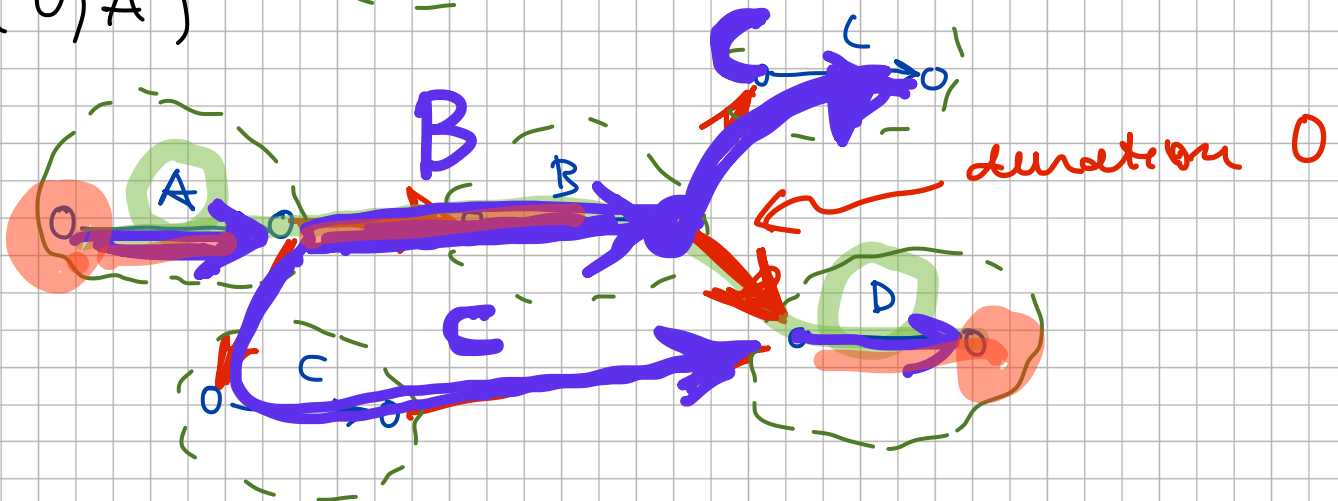
• ACTIVITIES on the NODES



• ACTIVITIES on the ARCS

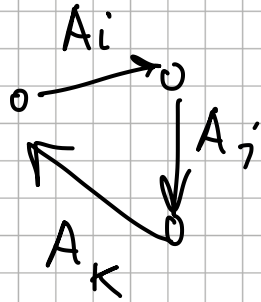


$G = (U, A)$



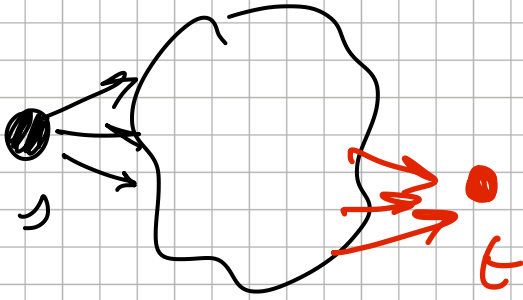
Properties

G does not contain any CIRCUIT

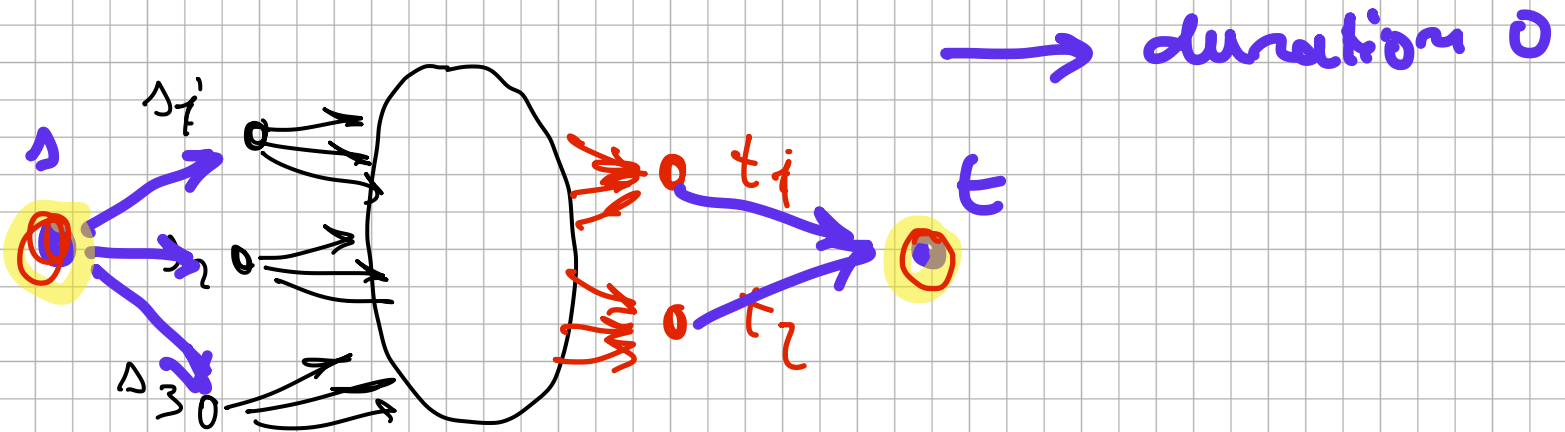


$A_i < A_j < A_k < A_i$
 \Rightarrow PR. INFEASIBLE

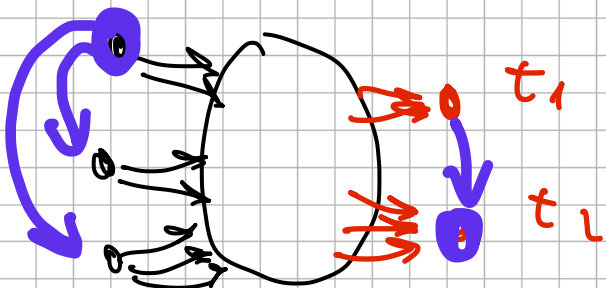
• \exists a START node $s : \delta^-(s) = \emptyset$



• \exists a FINAL node $t : \delta^+(t) = \emptyset$



H_p : ONLY one START / FINAL mode in G

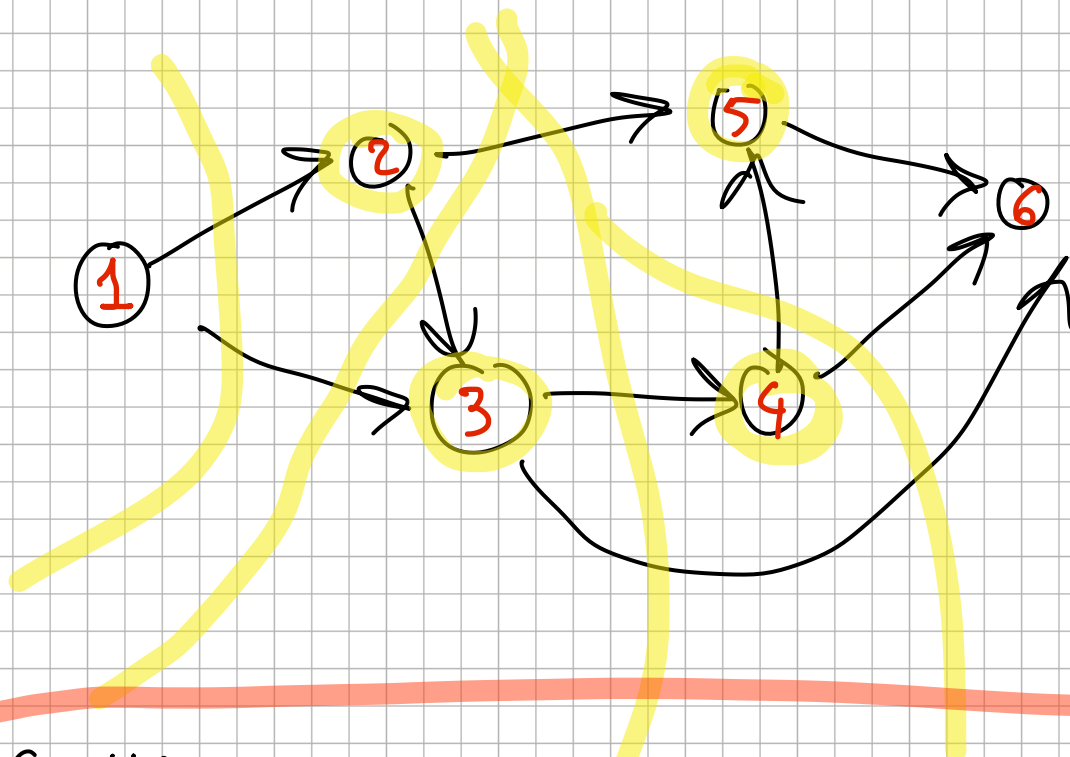


• HP: Nodes are in TOPOLOGICAL ORDER

$$(i) \rightarrow (j) \Rightarrow i < j$$

SIMPLE (FAST) ALG.

$O(|A|)$ time



COMPUTES THE MINIMUM DURATION
(**MAKES PAN**)

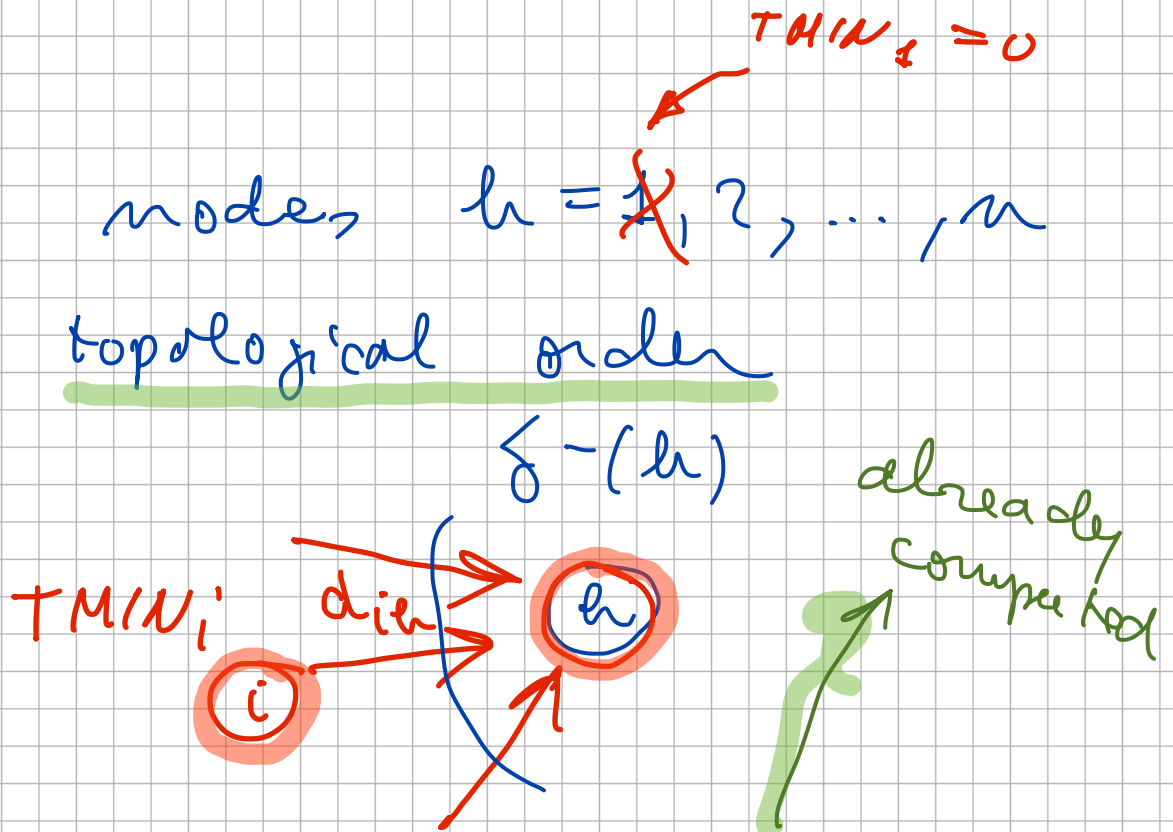
CPM alg. (CRITICAL
PATH
METHOD)

" PERT method "



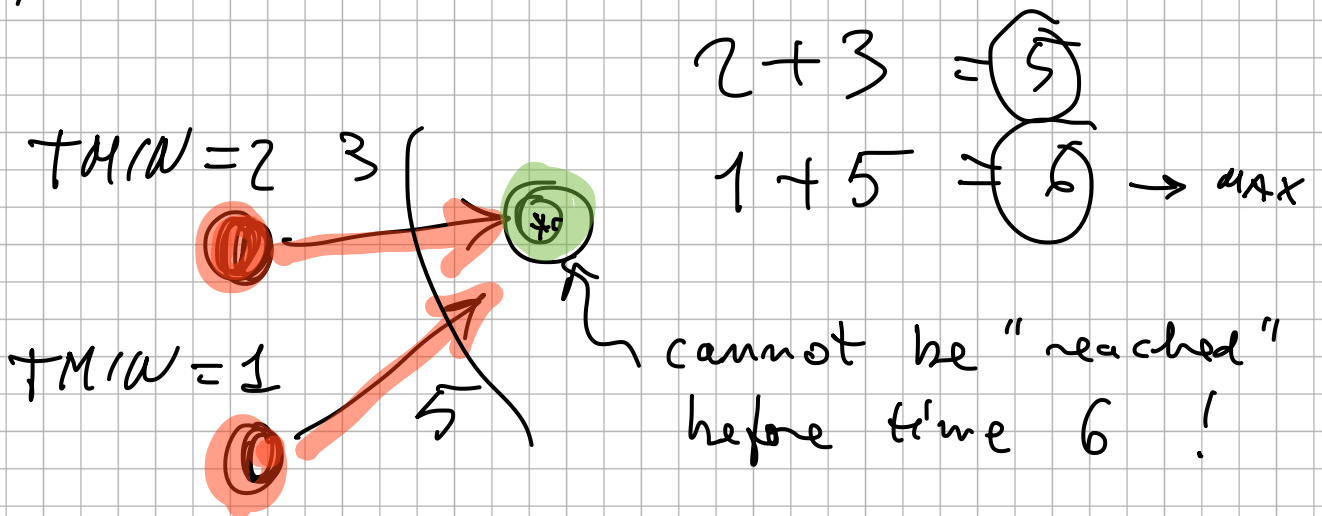
Compute $TMIN_h :=$ earliest possible time for "reaching" node h

Scan nodes $h = 1, 2, \dots, n$
 in topological order

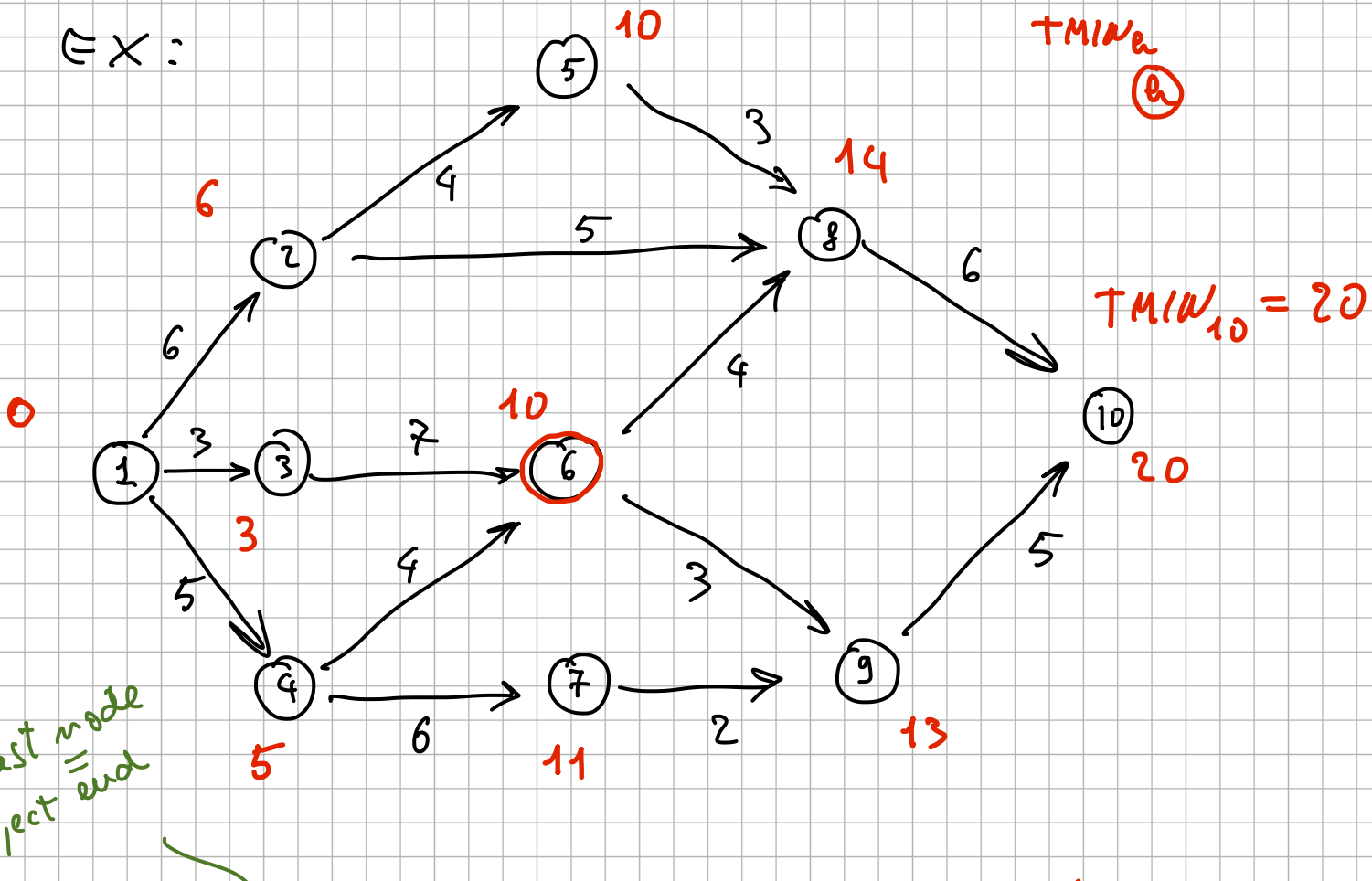


$$TMIN_h = \max \{ TMIN_i + dier : (i, h) \in \delta^-(h) \}$$

Why max?



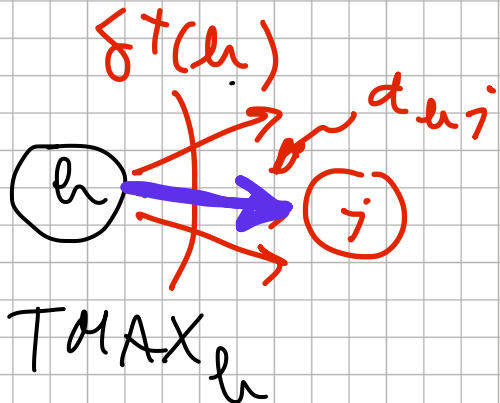
$E \times X:$



$TMIN_n =$ minimum duration of the project

Solution: start each activity $(i, j) \in A$ at the earliest-possible time, namely $TMIN_i$

SENSITIVITY ANALYSIS:

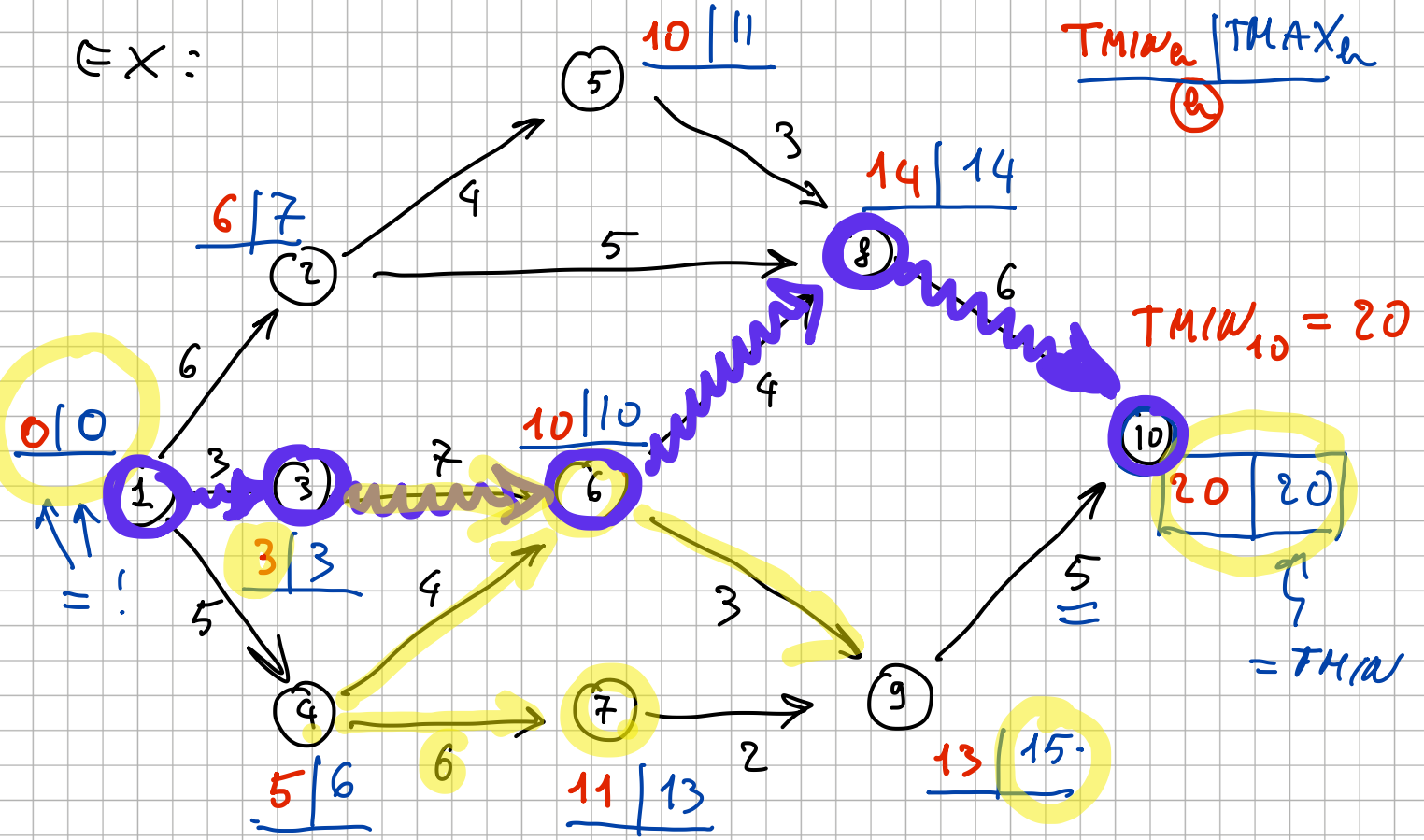


$$TMAX_h := \min \{ TMAX_j - d_{hj}, (h, j) \in \delta^+(h) \}$$

for $h = \cancel{n}, n-1, \dots, 1$

$TMAX_n := TMIN_n$

$\in X:$



⊙ CRITICAL NODE $TMIN_i = TMAX_i$

→ " ACTIVITY (i,j)

$$TMAX_j - TMIN_i = d_{ij}$$

GANTT CHART

