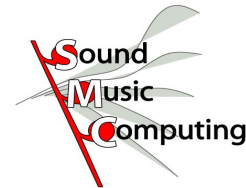


Sound rendering in Interactive Multimodal Systems

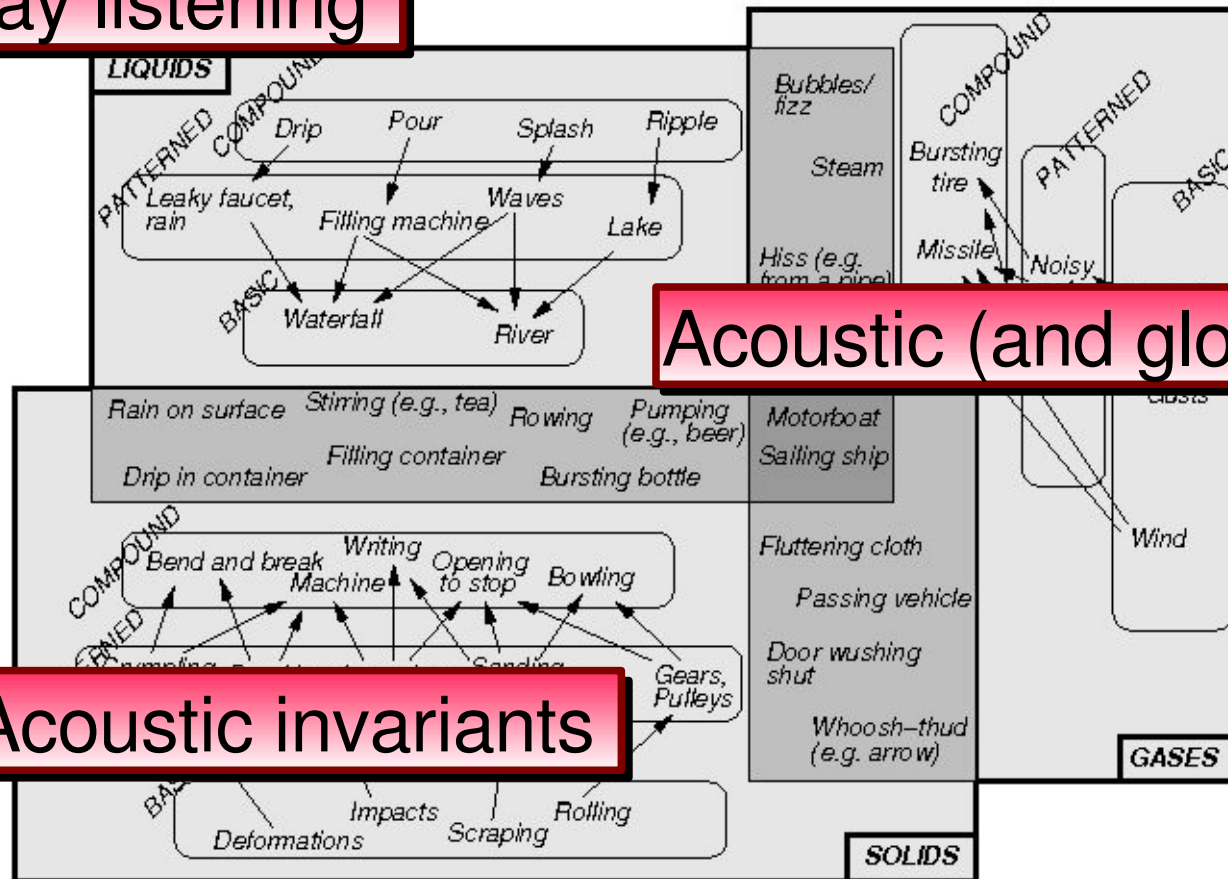
Federico Avanzini



- Background
 - Ecological Acoustics
 - Multimodal perception
- Auditory-visual rendering of egocentric distance
 - Binaural sound
 - Auditory cues for distance
 - Bimodal rendering: recent results, ongoing work
- Multimodal rendering of virtual objects
 - Synthesis of environmental sounds
 - Multimodal rendering architectures
 - Haptic-audio: recent results, ongoing work

Ecological psychology, Ecological acoustics

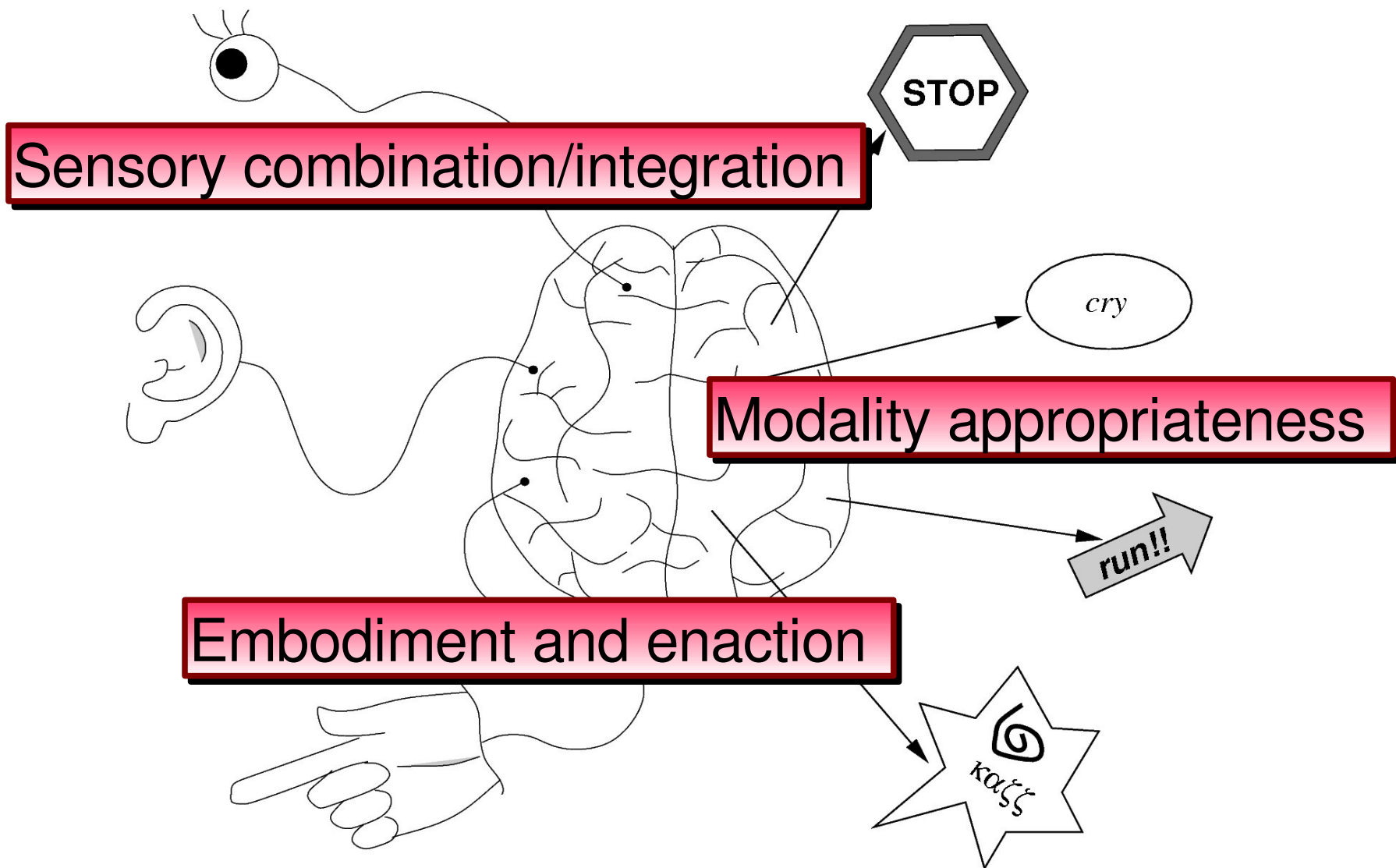
Everyday listening



Acoustic (and global) array

Acoustic invariants

Multimodal perception



The sound rendering pipeline

■ Modeling

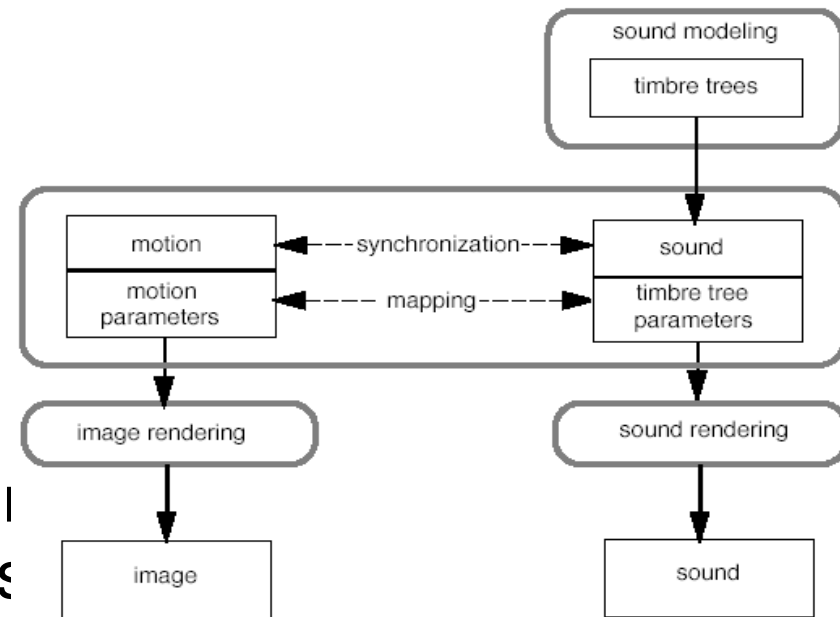
- Sound sources: resonating objects, interactions, ...
- Physical modeling

■ Synchronization

- With other modalities: mapping from motion to sound parameters latency, ...
- Physical modeling

■ Rendering

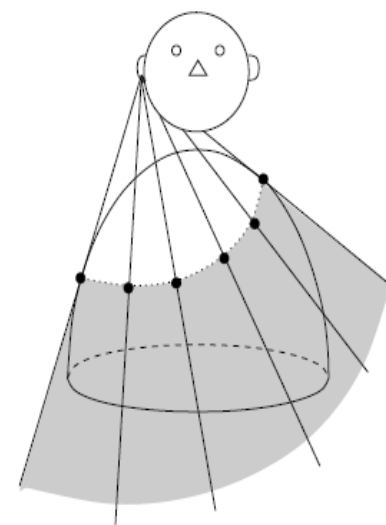
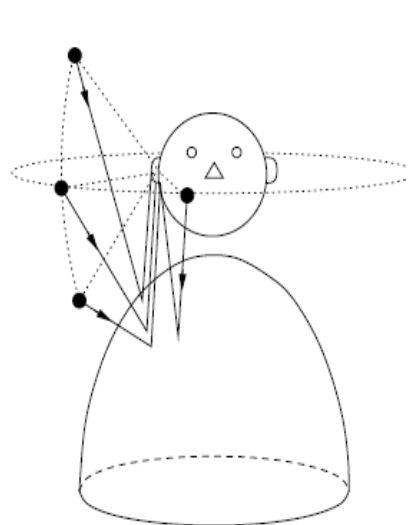
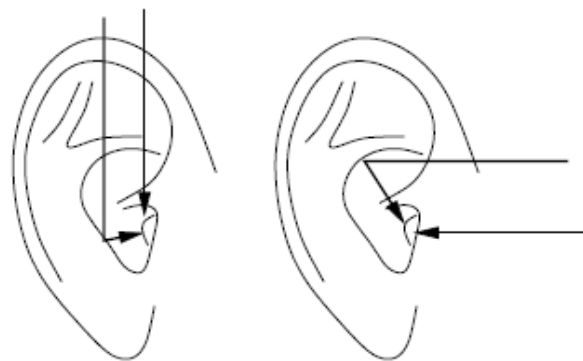
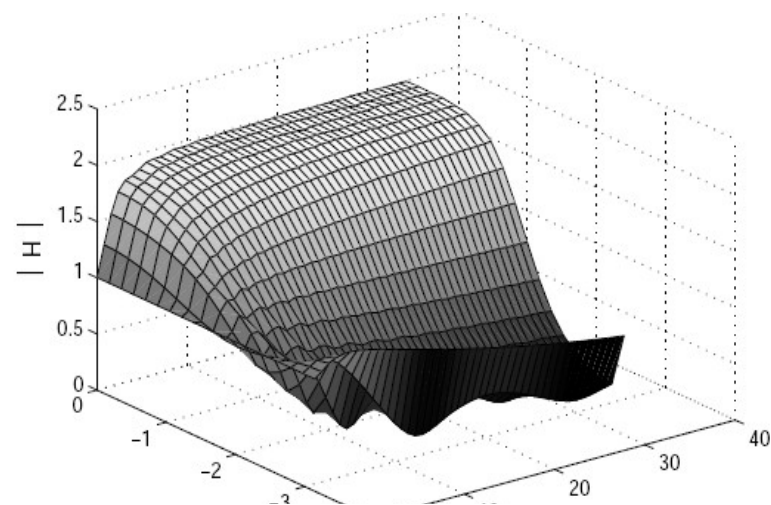
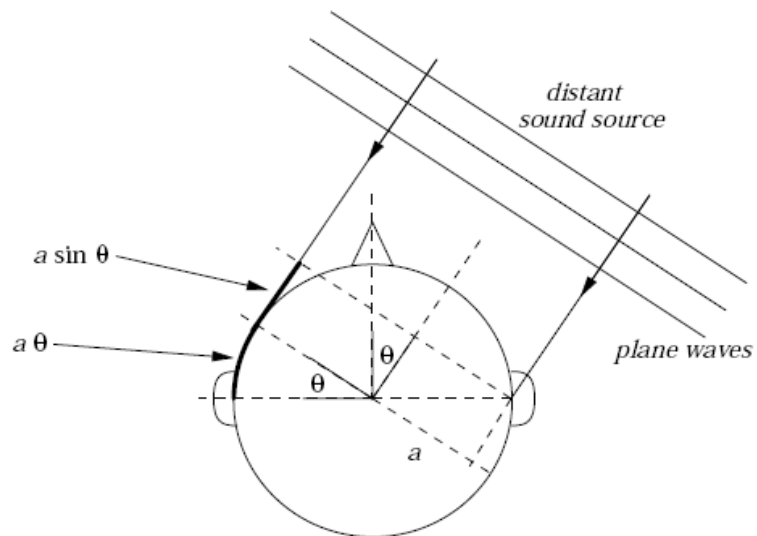
- Generate sound signals from models, in a given environment



J. K. Hahn, et al. Presence 1998

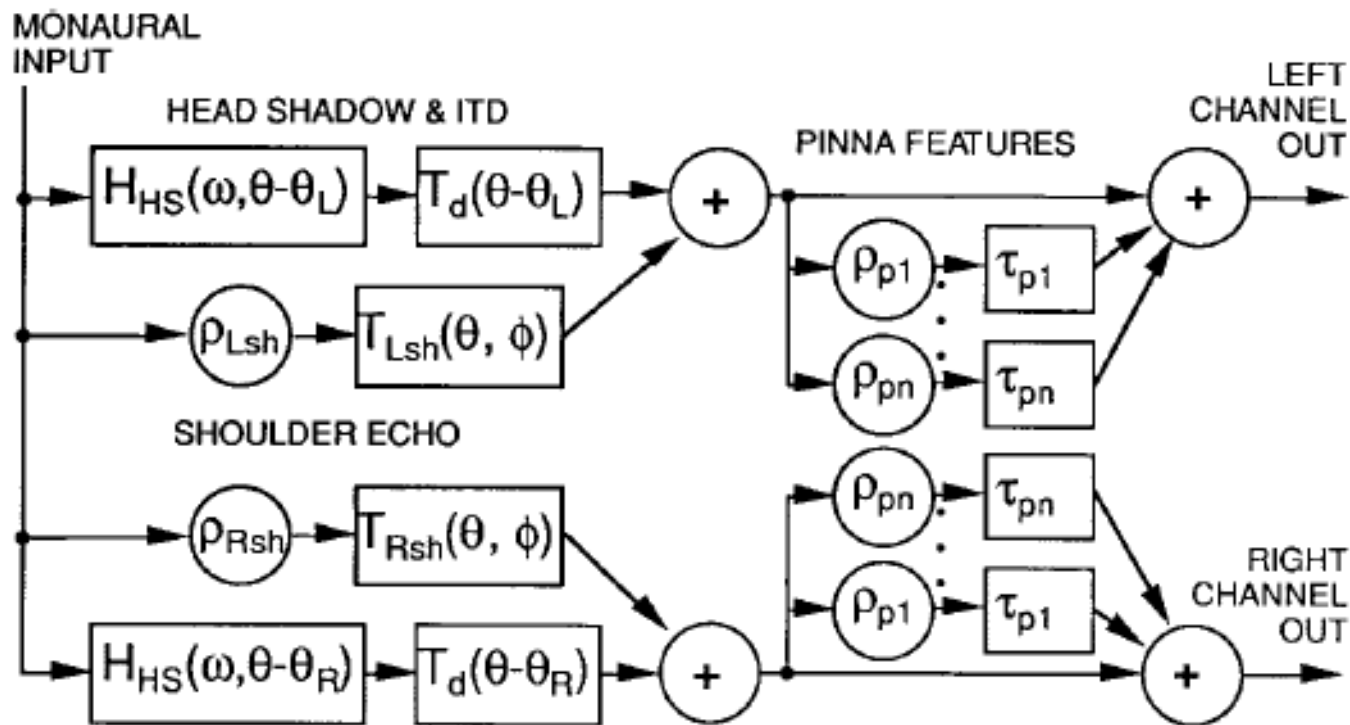
Auditory-visual rendering of egocentric distance

Binaural sound



Binaural sound

- Structural models (Duda and coworkers)

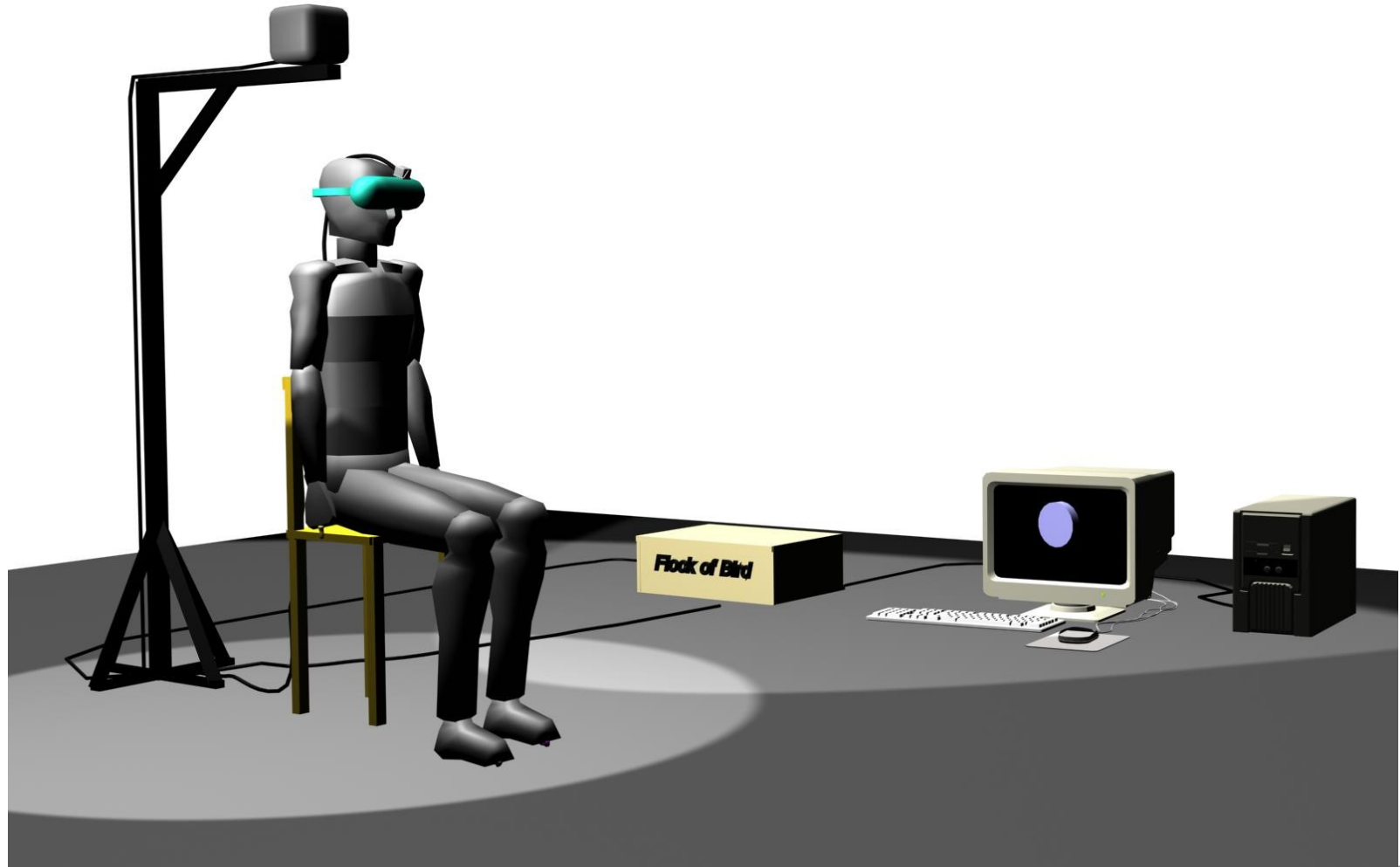




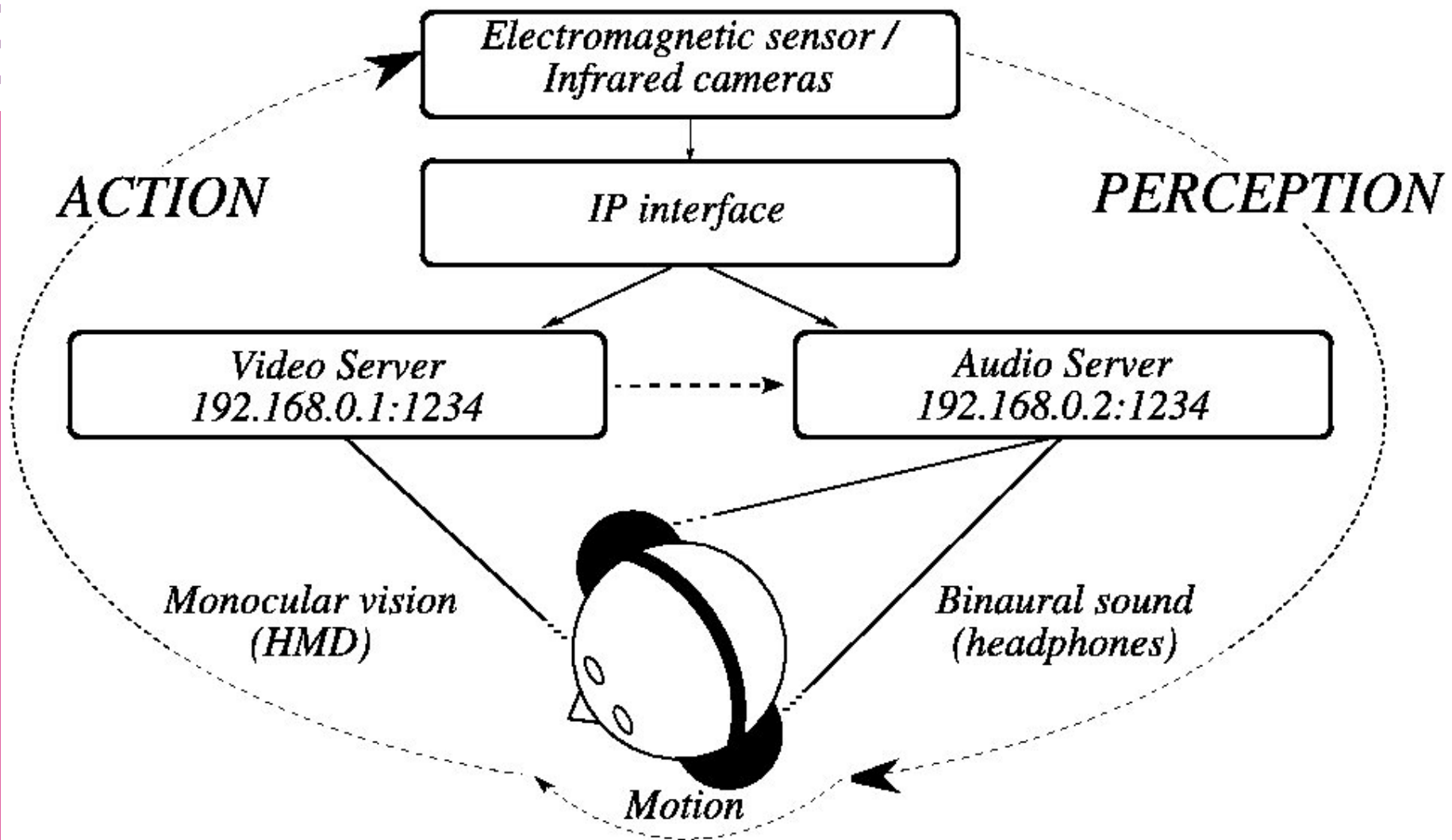
Auditory-visual rendering of egocentric distance

- Estimation of egocentric distance
 - Is an “enactive” task
 - Verbal judgements vs. action-driven judgments
- The problem of distance rendering is much studied in VR applications
- Auditory distance rendering is hard, auditory cues to distance are ambiguous
 - Static cues: intensity, R/D ratio, familiarity, distance-dependent spectral cues, auditory parallax
 - Dynamic cues: motion parallax, “acoustic tau”

Experimental setup

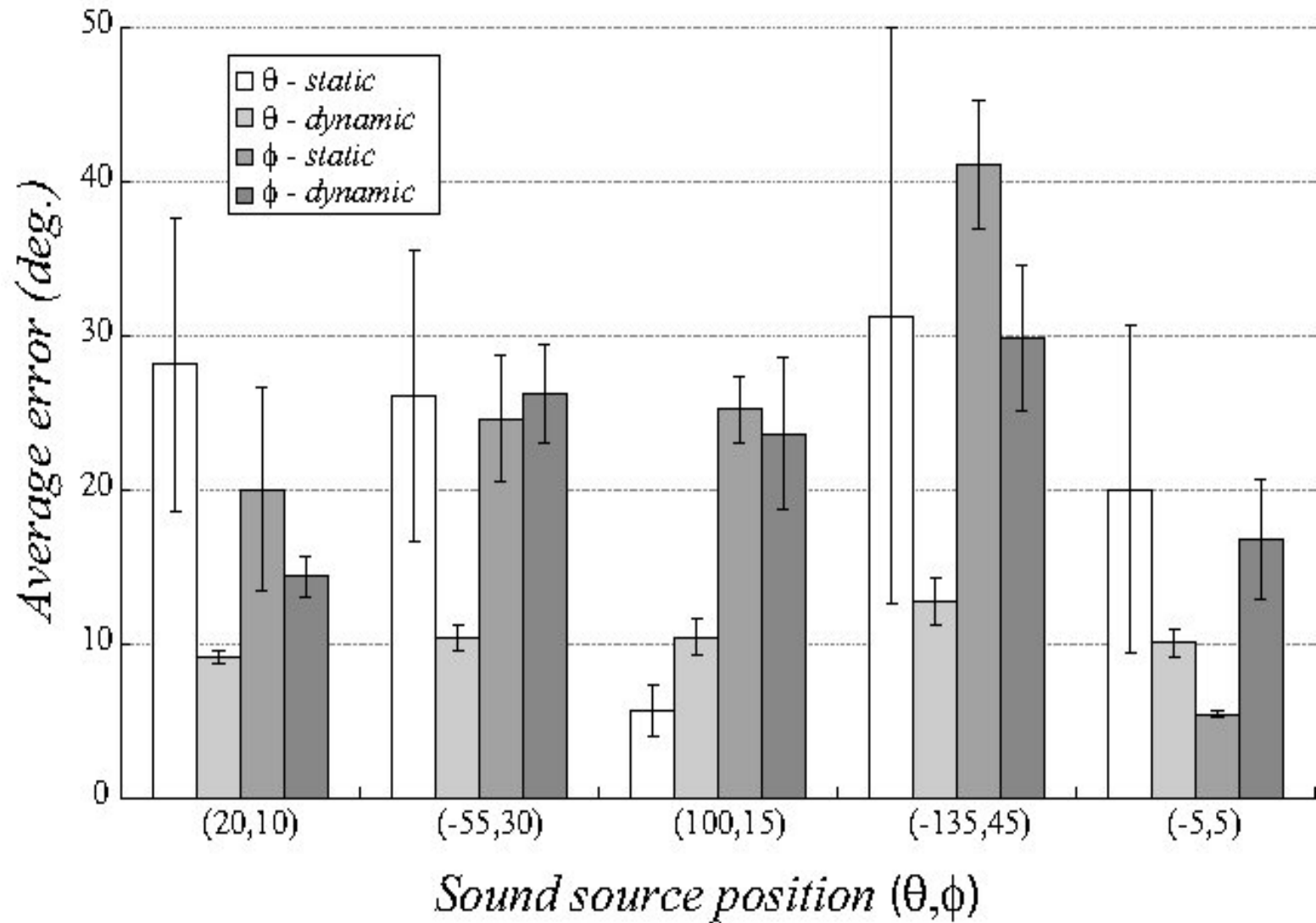


The rendering system





Preliminary exp. results: azimuth & elevation



Preliminary exp results: distance

- 10 subjects
- 9 stimuli (9 distances) presented in 3 conditions (visual only, audio only, audio-visual), and in active/passive settings
- Addition of audio improves distance estimation considerably
 - Even in “passive” settings (??)

Multimodal rendering of virtual objects

Sound Synthesis

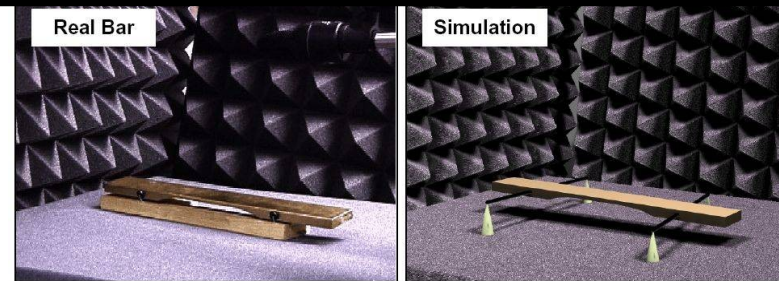
Contact sounds

K. van den Doel, P. G. Kry, and D. K. Pai. Proc. ACM SIGGRAPH 2001

- Modal synthesis
- Finite Element Models
- Other structures
(e.g., WGs) are less used



J. F. O'Brien, P. R. Cook, and G. Essl. Proc. ACM SIGGRAPH 2001



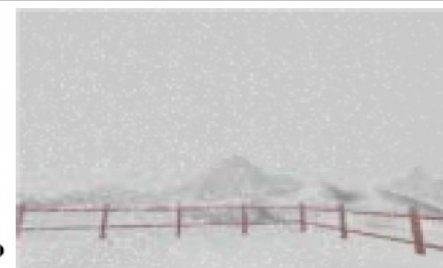
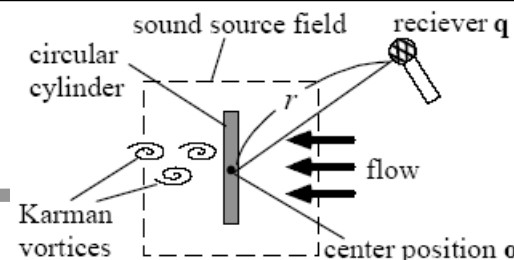
K. van den Doel. Proc. ICAD 2004



Other typologies

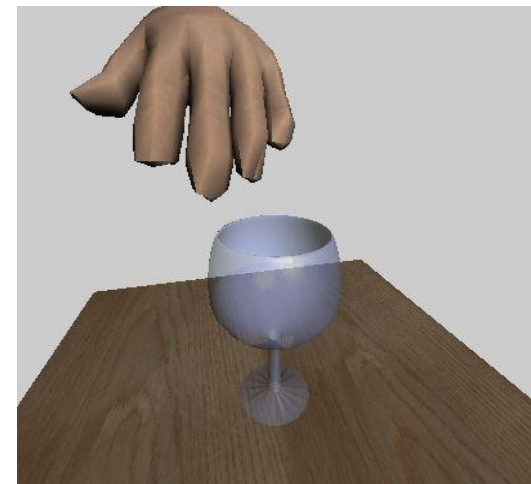
- Liquids
- Aerodynamic sounds
- More research needed

Y. Dobashi, T. Yamamoto, and T. Nishita Proc. ACM SIGGRAPH 2003



Sound models

- Basic sound models
 - Modal resonators
 - Non-linear interactions (impact, friction)
- Building blocks for *patterned* and *compound* environmental sounds
 - Toward a hierarchical taxonomy of sound models
- Link to ecological dimensions
 - Mappings from sound features to ecological dimensions are known
 - Need for mappings from physical parameters to relevant sound features



Physical models and ecological mappings

■ Modal synthesis

$$\ddot{q}_n(t) + g_n \dot{q}_n(t) + \omega_n^2 q_n(t) = \frac{1}{m_n} f_A(t)$$

- modal frequencies depend on *shape* and geometry
- *material* determines decay characteristics
- amplitudes of partials depend on strike location

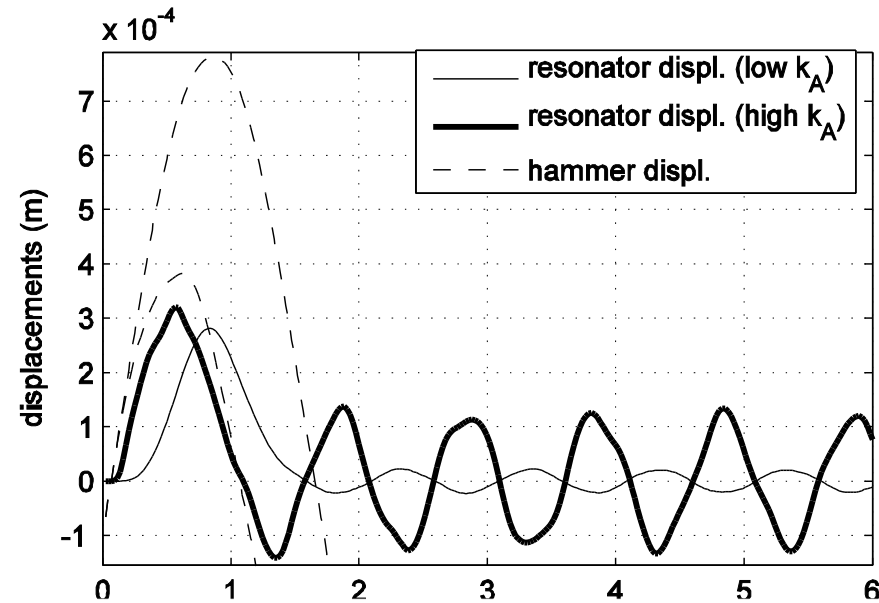
■ Impact force (Hunt-Crossley - *ASME J. Applied Mech.* 1975)

$$f_A(x(t), v(t)) = \begin{cases} k_A x(t)^\alpha + \lambda_A x(t)^\alpha \cdot v(t) & x \geq 0, \\ 0 & x < 0, \end{cases}$$

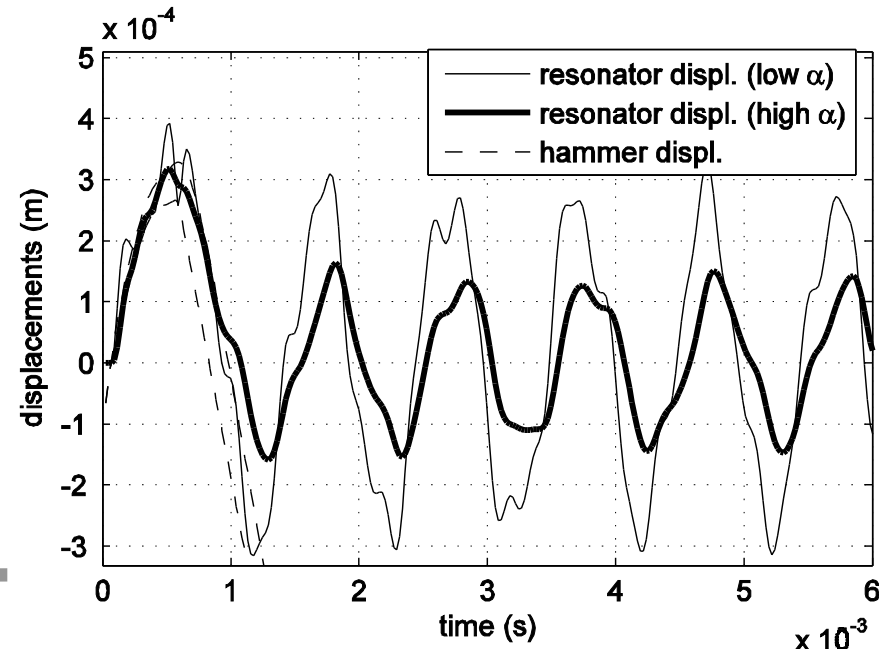
- Parameters of contact force provide control over other ecological dimensions of the sound events
- E.g., auditorily perceived stiffness.

Examples of attack transients

- Varying the force stiffness



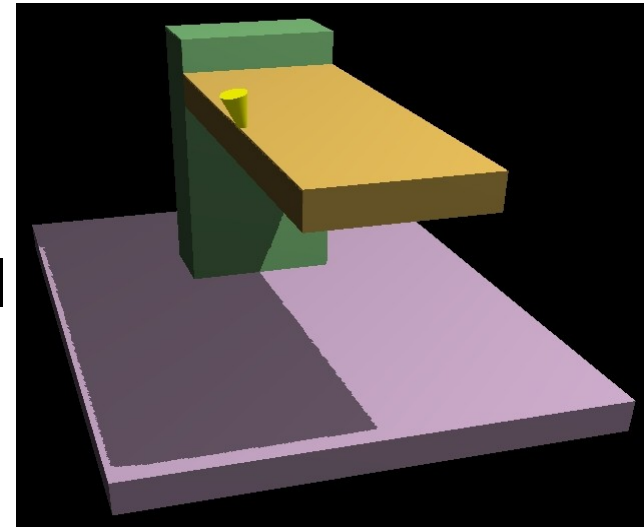
- Varying the force exponent



Multimodal rendering of virtual objects

■ Immersion

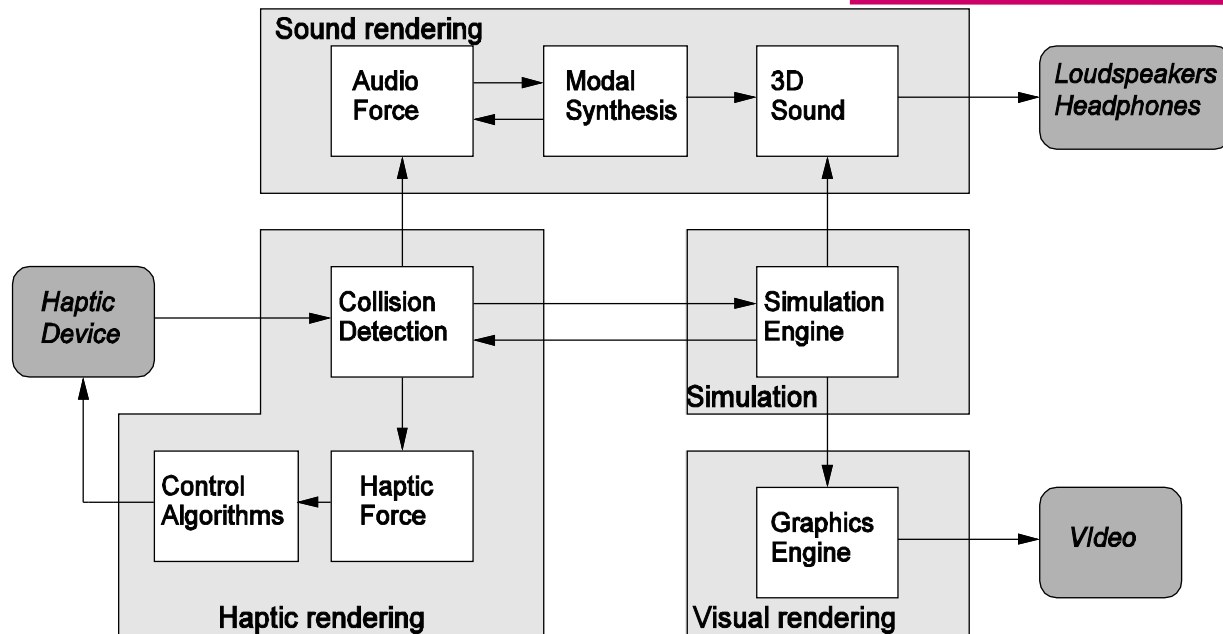
- Properly designed/synchronized multimodal display provides greater immersion in a VE than a hi-fi visual display alone.
- The range of object properties conveyed to the user can be enhanced



■ Physical models

- Interactivity and ease in associating motion to sound control
- Sound-rendering attributes can be incorporated into data structures that provide multimodal encoding of object properties

A multimodal rendering architecture



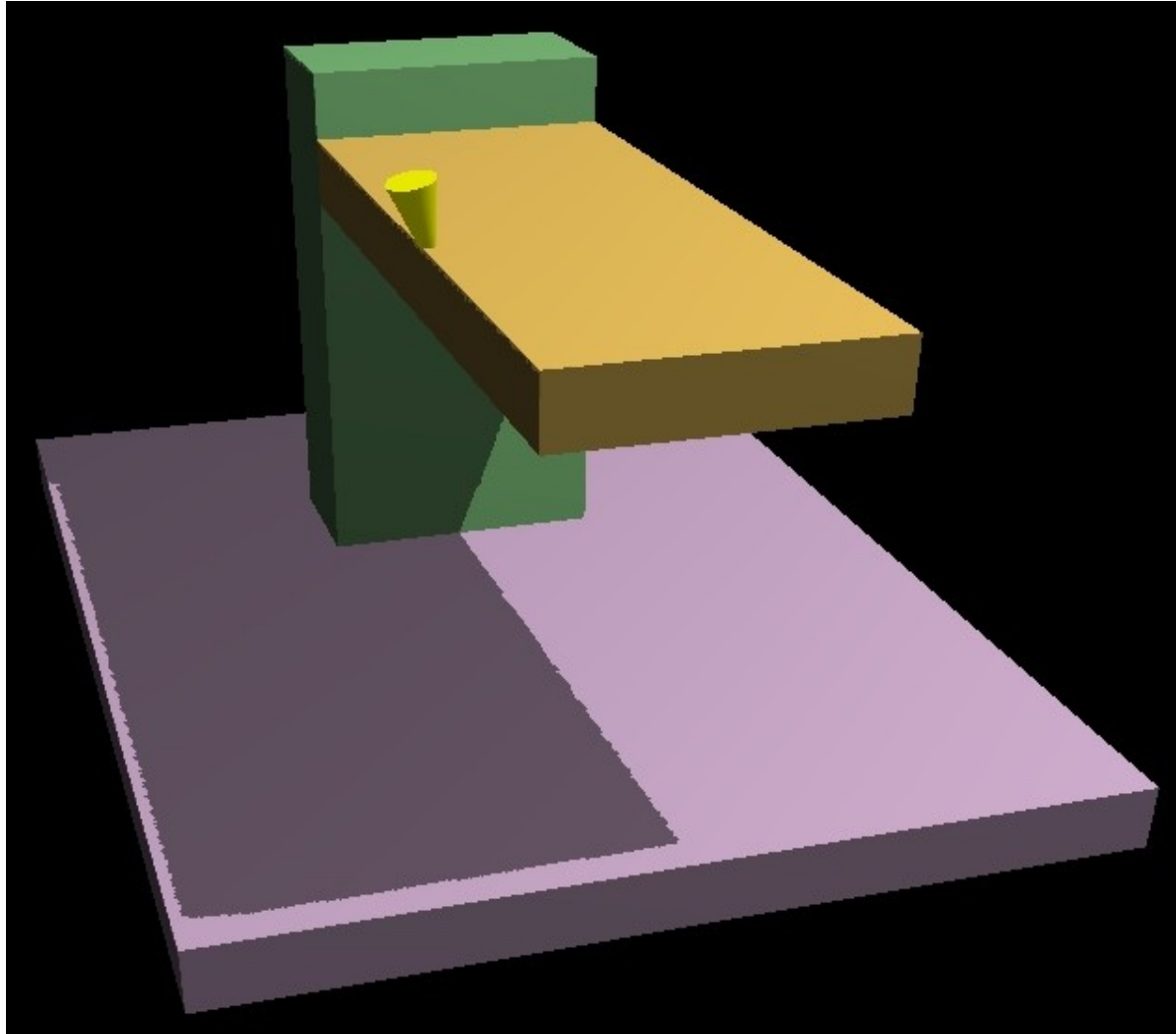
- Need for synchronization and low intermodal latency
- Sound computation triggered by contact detection
- Contact force computation embedded in the audio rendering thread
- Current (well... future...) work: integrate sound models into unified scene graph APIs

Bimodal perception of stiffness

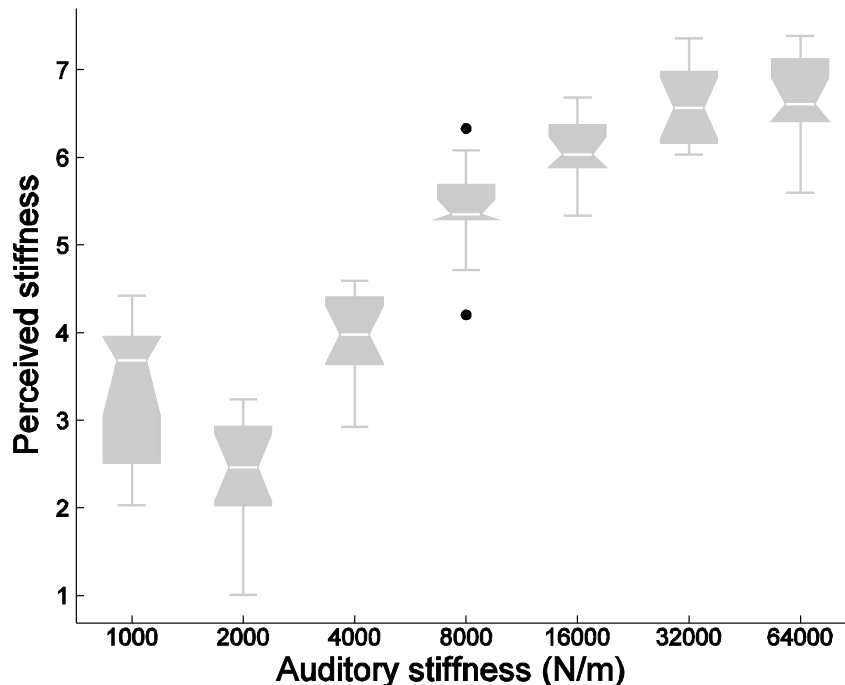
- Goal
 - Assess relative contributions of haptic and auditory information to bimodal judgments of *contact stiffness*
 - It's the prototypical haptic task!
- Stimuli
 - Graphic display does not change between conditions
 - In every condition same (400N/m) haptic stiffness
 - Auditory stiffness is the only parameter of the sound model which is varied between stimuli (7 levels)
- Procedure
 - 18 participants instructed to judge stiffness through absolute magnitude-estimation (scale from 1 to 8)



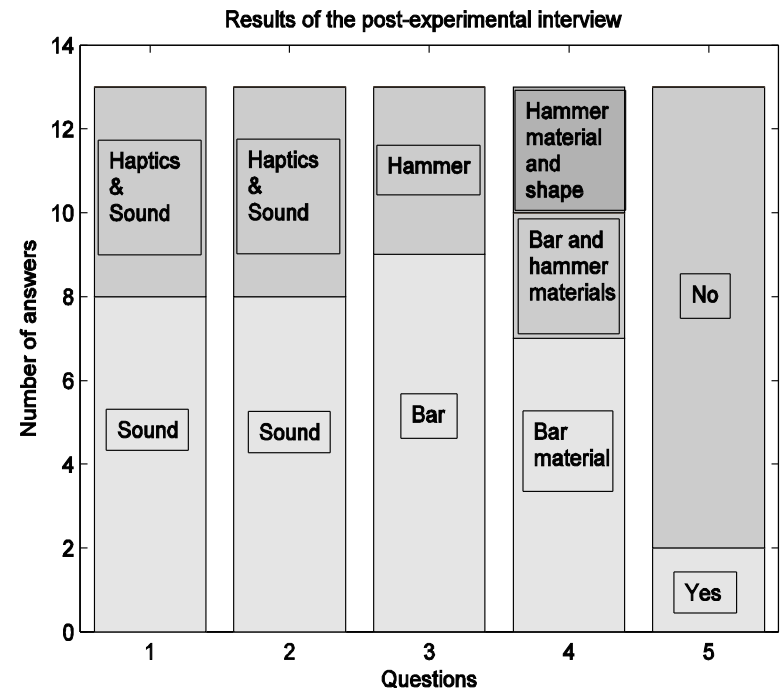
An experimental session



- Magnitude estimates
 - Averaged across repetitions
 - Normalized with respect to grand mean across participants

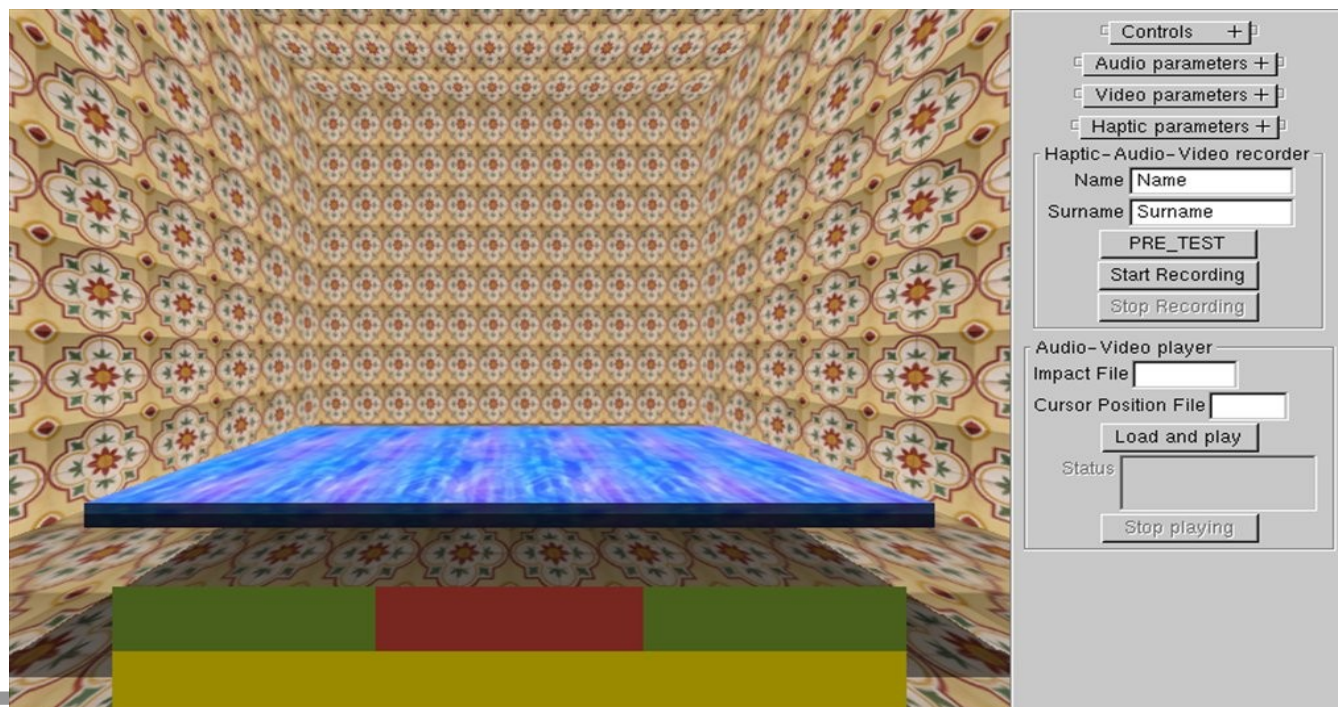


- Post-experimental interview
 - Auditory illusion: haptic stiffness was perceived to vary

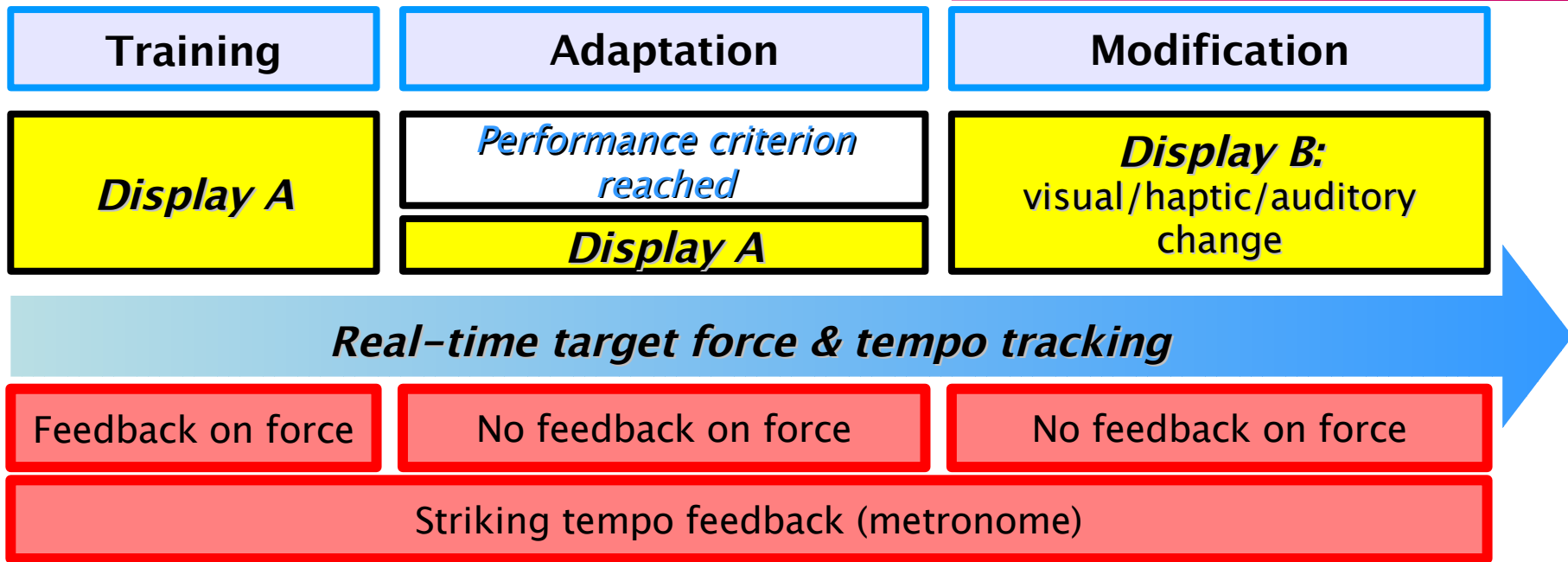


Sensory integration in percussion performance

- Focus on performance
 - We avoid judgements based on verbal descriptions
 - We focus on knowledge generated through action
- Task
 - Strike an object with given impact force & given tempo



Experimental design



- Unimodal change: haptic k , auditory k , visual speed
- Performance variation induced by display change proportional to perceptual relevance of interested modality
- Possible extension: study performer kinematics