Space-Round Tradeoffs for MapReduce Computations

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MapReduce

- Introduced in [Dean & Ghemawat, OSDI 2004]
- Programming paradigm for large data sets
- Typically used on clusters of commodity computers
- Widely used in many scenarios: log processing, data-mining, scientific computations,...

MapReduce (2)

- Eases programmer tasks
 - The runtime system manages low-level details
 - Focus on the problem, not on the platform

Inspired by functional programming

- Algorithm is a sequence of rounds
 - Map/Reduce functions

A MapReduce round



Previous work

- Modeling efforts
 - [Feldman et al, SODA 2008]
 - [Karloff et al, SODA 2010]
 - [Goodrich et al, ISAAC 2011]

- Algorithms
 - Graph problems, e.g. [Suri et al, WWW 2011][Lattanzi et al, SPAA 2011]
 - Clustering, e.g. [Ene et al, KDD 2011]

Our results

- 1. Computational model for MapReduce
 - Overcomes some limitations of previous models
 - Two parameters describing the local and aggregate space constraints

2. Algorithms for sparse/dense matrix multiplication

- Tradeoffs between performance and space parameters
- 3. Applications based on matrix multiplication
 - Matrix inversion and matching

The MR(m,M) model

- Based on [Karloff et al, SODA 2010]
- Clear separation between model and underlying infrastructure
- Maintains functional flavor
- No need to distinguish between mappers and reducers
- An MR algorithm is a sequence of rounds

An MR round



Tradeoffs

- Complexity measure: number of rounds
 - Rationale: shuffling is the expensive operation
- Parameters *m* and *M*:
 - *m*: max reducer size (limits the number of pairs received by a reducer)
 - M: max amount of total space (max number of pairs in a round)
 - Allow for a flexible use of parallelism: e.g., *M/m* reducers of size *m*, or *M* reducers of size *O(1)*
- We aim at deriving tradeoffs between space and number of rounds

Matrix multiplication on MR

- Lower and upper bounds for
 - Dense-dense matrix multiplication
 - Spare-sparse matrix multiplication
 - three variants (D1, D2, R1)
 - Estimating density of product matrix

- Sparse-dense matrix multiplication

Optimal space-round tradeoffs in many cases

Notation

• A, B, C=AxB: matrices of size $\sqrt{n} x \sqrt{n}$

- Divide into submatrices of size $\sqrt{m} x \sqrt{m}$
 - Partition the $(n/m)^{3/2}$ multiplications into $(n/m)^{1/2}$ groups
 - Each submatrix appears once in each group
- \overline{n} : number of nonzero entries in A and B
- *o*: number of nonzero entries in C (not known!)

Dense-dense case

- Each group requires space 3*n*
- In each round: compute multiplications within *M/3n* groups
- Number of rounds

$$O\left(\frac{n^{3/2}}{M\sqrt{m}} + \log_m n\right)$$

• Constant number of rounds if m = poly(n) and $M = \Omega(n^{3/2}/\sqrt{m})$

Sparse-sparse: Deterministic D1

- Column-row product: compute all nonzero products between the *i*-th column of A and *i*-th row of B (nonzero products could be < n)
- Compute the \sqrt{n} column-row products into phases
- In each phase:
 - number of column-row products in the phase computed via prefix-sum
 - no more than M nonzero products

Sparse-sparse: Deterministic D1 (2)

Number of rounds

$$O\left(\frac{\overline{n}\min(\overline{n},\sqrt{n})}{M}\log_m n\right)$$

- Constant number of rounds if *m=poly(n)* and M sufficiently large
- Extends to the sparse-dense case
- Inefficient use of reducer space *m*

Sparse-sparse: Deterministic D2

- Clever implementation of dense-dense algorithm leveraging on the sparsity
- Number of groups in each phase computed through a prefix sum based on the space requirements of involved submatrices
- Number of rounds

$$O\left(\frac{(\bar{n}+\bar{o})\sqrt{n}}{M\sqrt{m}}\log_{m}n\right)$$

Constant round complexity if *m=poly(n)*, *M* sufficiently large

Sparse-sparse: Randomized R3

- D2 can be improved if \overline{o} is known
 - Avoid prefix sums by processing M/(n+o) groups per phase

An approximation to o is given by a randomized algorithm

• Number of rounds

$$O\left(\frac{(\overline{n}+\overline{o})\sqrt{n}}{M\sqrt{m}}+\log_m n\right)$$

Density of product matrix

- We use streaming sketches [Bar-Yossef, RANDOM 2002]
 - Data-structure for computing number of distinct values in a stream with small space

- Size of output matrix:
 - For each nonzero product, assign to pair (a_{ik}, b_{kj}) the value (i, j)
 - Number of nonzero entries in C = number of distinct values (using sketches)

Lower bounds

- Only semiring operations (no Strassen)
- Matrices of size $\sqrt{n} x \sqrt{n}$
- *n* nonzero entries per matrix
- Number of rounds (based on [Hong & Kung, STOC 81])

$$\Omega\left(\frac{\bar{n}\min(\bar{n},\sqrt{n})}{M\sqrt{m}} + \log_m n\right)$$

• Constant rounds \rightarrow data replication

Applications

• We use dense-dense matrix multiplication for:

- Inverse of a triangular matrix in constant rounds
- Inverse of a general matrix in O(log n) rounds
- Approximate inverse of a general matrix in O(log n) rounds (and less space)
- Perfect matching in O(log n) rounds

Conclusion

 Our results provide evidence that nontrivial tradeoffs can be exercised between space requirement and performance

- Future work:
 - Tradeoffs for other problems, e.g. graphs, data-mining
 - Experimental evaluation of the model and algorithms

Thank you!

